

# Statix

## Checking & Generating Programs

Hendrik van Antwerpen  
*Delft University of Technology*

FP Seminar, Chalmers, 30 August 2019

# Type System Specifications

*Typing*  $\Gamma \vdash t : T$

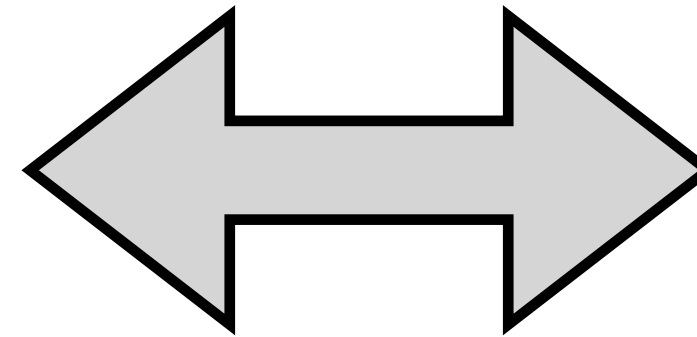
$$\frac{x : T \in \Gamma}{\Gamma \vdash x : T} \quad \text{(T-VAR)}$$

$$\frac{\Gamma, x : T_1 \vdash t_2 : T_2}{\Gamma \vdash \lambda x : T_1. t_2 : T_1 \rightarrow T_2} \quad \text{(T-ABS)}$$

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 t_2 : T_{12}} \quad \text{(T-APP)}$$

$$\frac{\Gamma, X <: T_1 \vdash t_2 : T_2}{\Gamma \vdash \lambda X <: T_1. t_2 : \forall X <: T_1. T_2} \quad \text{(T-TABS)}$$

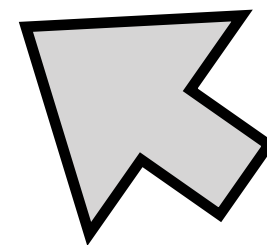
$$\frac{\Gamma \vdash t_1 : \forall X <: T_{11}. T_{12} \quad \Gamma \vdash T_2 <: T_{11}}{\Gamma \vdash t_1 [T_2] : [X \mapsto T_2] T_{12}} \quad \text{(T-TAPP)}$$

$$\frac{\Gamma \vdash t : S \quad \Gamma \vdash S <: T}{\Gamma \vdash t : T} \quad \text{(T-SUB)}$$


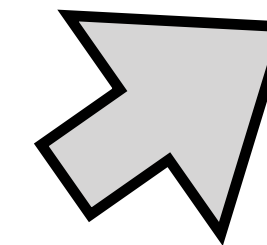
```

let rec typeof ctx t =
  match t with
  | TmVar(fi,i,_) -> getTypeFromContext fi ctx i
  | TmAbs(fi,x,tyT1,t2) ->
    let ctx' = addbinding ctx x (VarBind(tyT1)) in
    let tyT2 = typeof ctx' t2 in
    TyArr(tyT1, typeShift (-1) tyT2)
  | TmApp(fi,t1,t2) ->
    let tyT1 = typeof ctx t1 in
    let tyT2 = typeof ctx t2 in
    (match tyT1 with
     | TyArr(tyT11,tyT12) ->
       if (=) tyT2 tyT11 then tyT12
       else error fi "parameter type mismatch"
     | _ -> error fi "arrow type expected")
  | TmTABS(fi,tyX,t2) ->
    let ctx = addbinding ctx tyX TyVarBind in
    let tyT2 = typeof ctx t2 in
    TyAll(tyX,tyT2)
  | TmTAPP(fi,t1,tyT2) ->
    let tyT1 = typeof ctx t1 in
    (match tyT1 with
     | TyAll(_,tyT12) -> typeSubstTop tyT2 tyT12
     | _ -> error fi "universal type expected")
  
```

Declarative  
Typing Rules



Executable  
Type Checker



**Typing Rules**  $\mathcal{G}, s \vdash e : t$

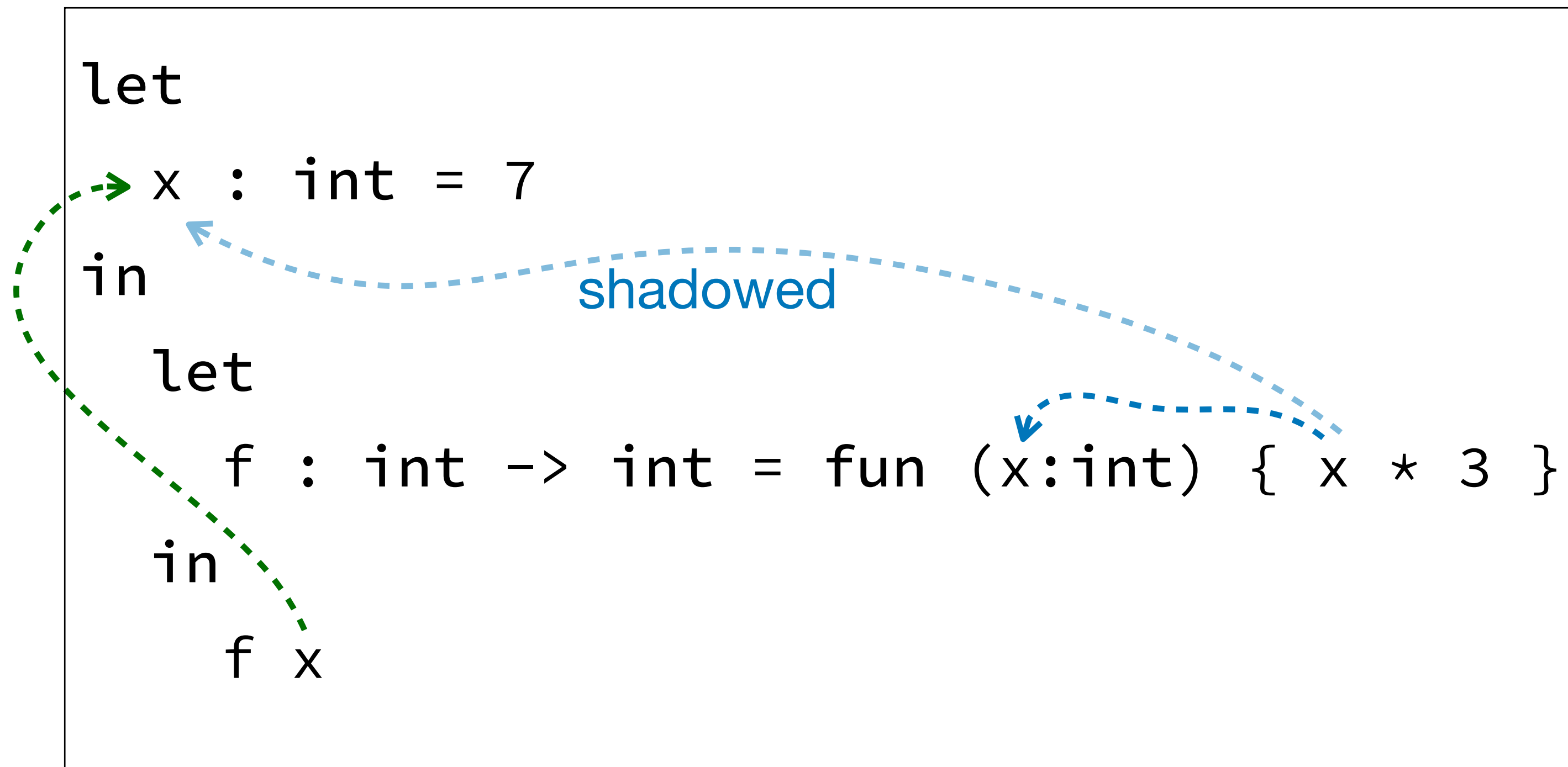
$$\text{(STLC-Num)} \frac{}{s \vdash z : \text{num}} \quad \text{(STLC-Plus)} \frac{s \vdash e_1 : \text{num} \quad s \vdash e_2 : \text{num}}{s \vdash e_1 + e_2 : \text{num}}$$

$$\text{(STLC-Fun)} \frac{\forall s_2 \quad s_2 \xrightarrow{P} s_1 \quad s_2 \dashv\vdash x_i : t_1 \quad s_2 \vdash e : t_2}{s_1 \vdash \text{fun } (x_i : t_1) \{ e \} : t_1 \rightarrow t_2}$$

$$\text{(STLC-Id)} \frac{\text{DECL}(x_i), P^*, \leq_T, <_l \vdash p : s \dashv\vdash x_j : t}{s \vdash x_i : t} \quad \text{(STLC-App)} \frac{s \vdash e_1 : t_1 \rightarrow t_2 \quad s \vdash e_2 : t_1}{s \vdash e_1 e_2 : t_2}$$

$$\text{(STLC-Let)} \frac{s_1 \vdash e_1 : t_1 \quad \forall s_2 \quad s_2 \xrightarrow{P} s_1 \quad s_2 \dashv\vdash x_i : t_1 \quad s_2 \vdash e_2 : t_2}{s_1 \vdash \text{let } x_i = e_1 \text{ in } e_2 : t_2}$$

# Binding: Lexical



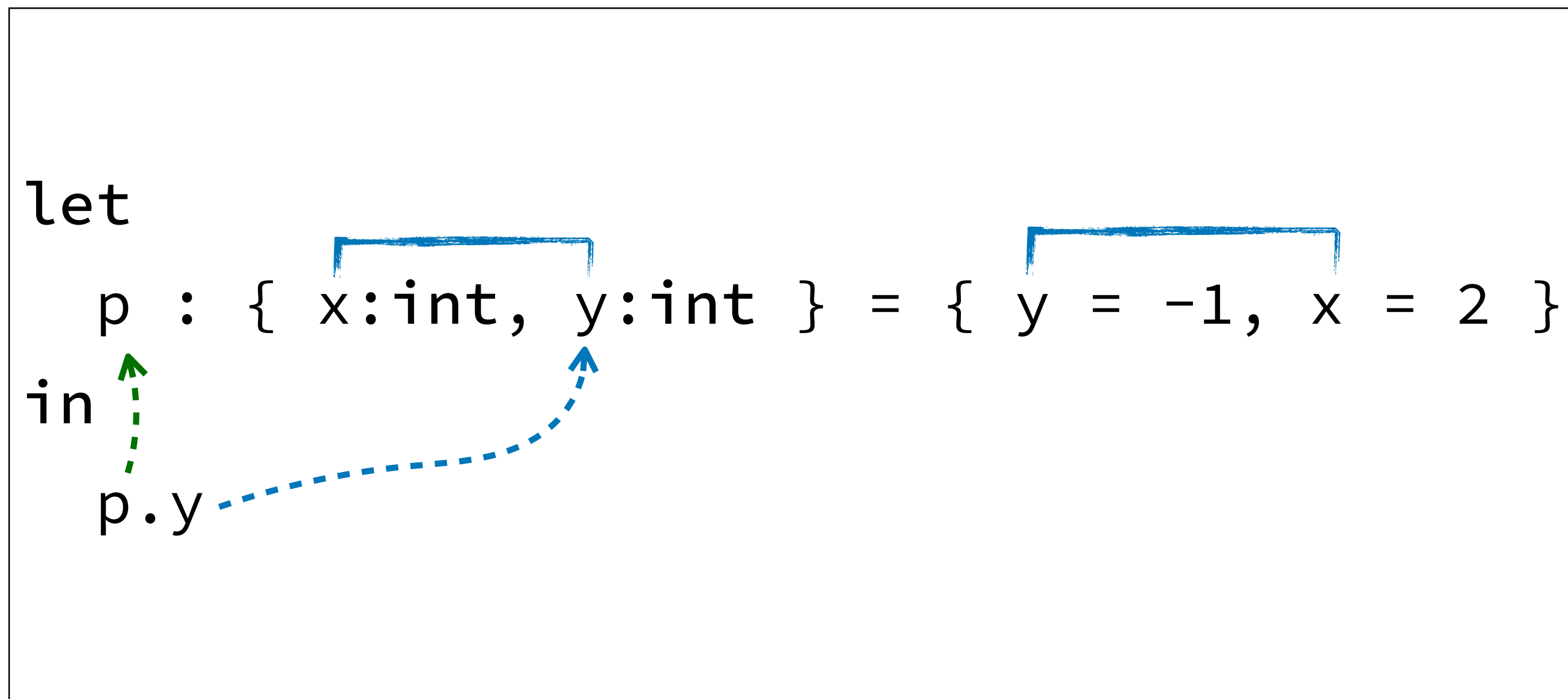
## Representation

- Typing environment
- Ordered list of name-types

## Execution order

- Constructed top-down

# Binding: Structural Records



## Representation

- Unordered map of fields-types

## Execution order

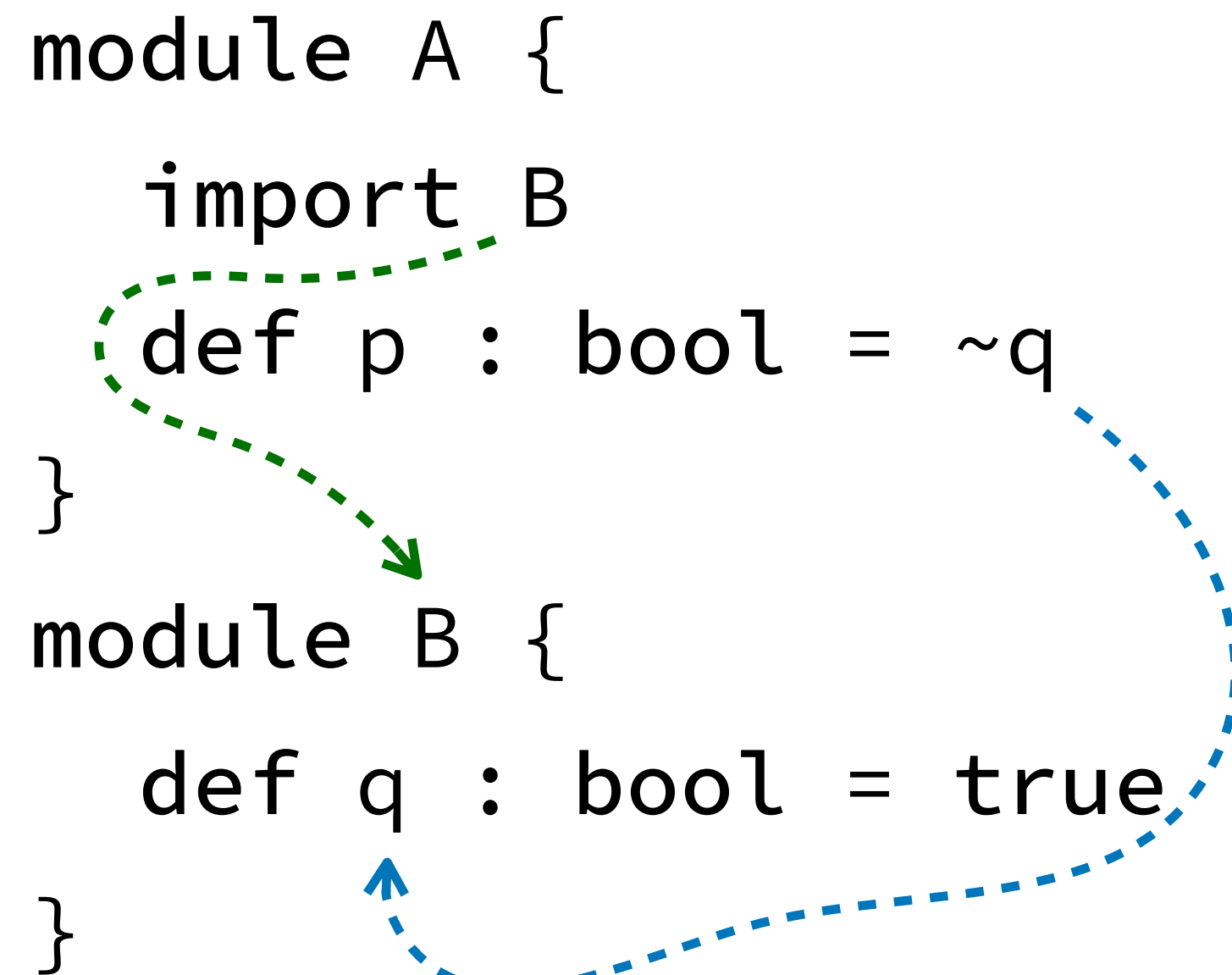
- Interleaved type checking and name resolution

In general:

- Types expose the scope structure of the underlying data
- Often language-specific representations (e.g., class types)

# Binding: Modules

```
module A {  
  import B  
  def p : bool = ~q  
}  
module B {  
  def q : bool = true  
}
```



## Representation

- Global module table (MT)
- Name-interface pairs
- Often language-specific

## Execution order

- Staged MT construction and module body checking

# Common Binding Representations in Specifications

## Binding Representation

Many different representations  
Often language-specific  
Ad-hoc, not reusable

## Execution Order

Interleaving  
Staging  
Not declarative

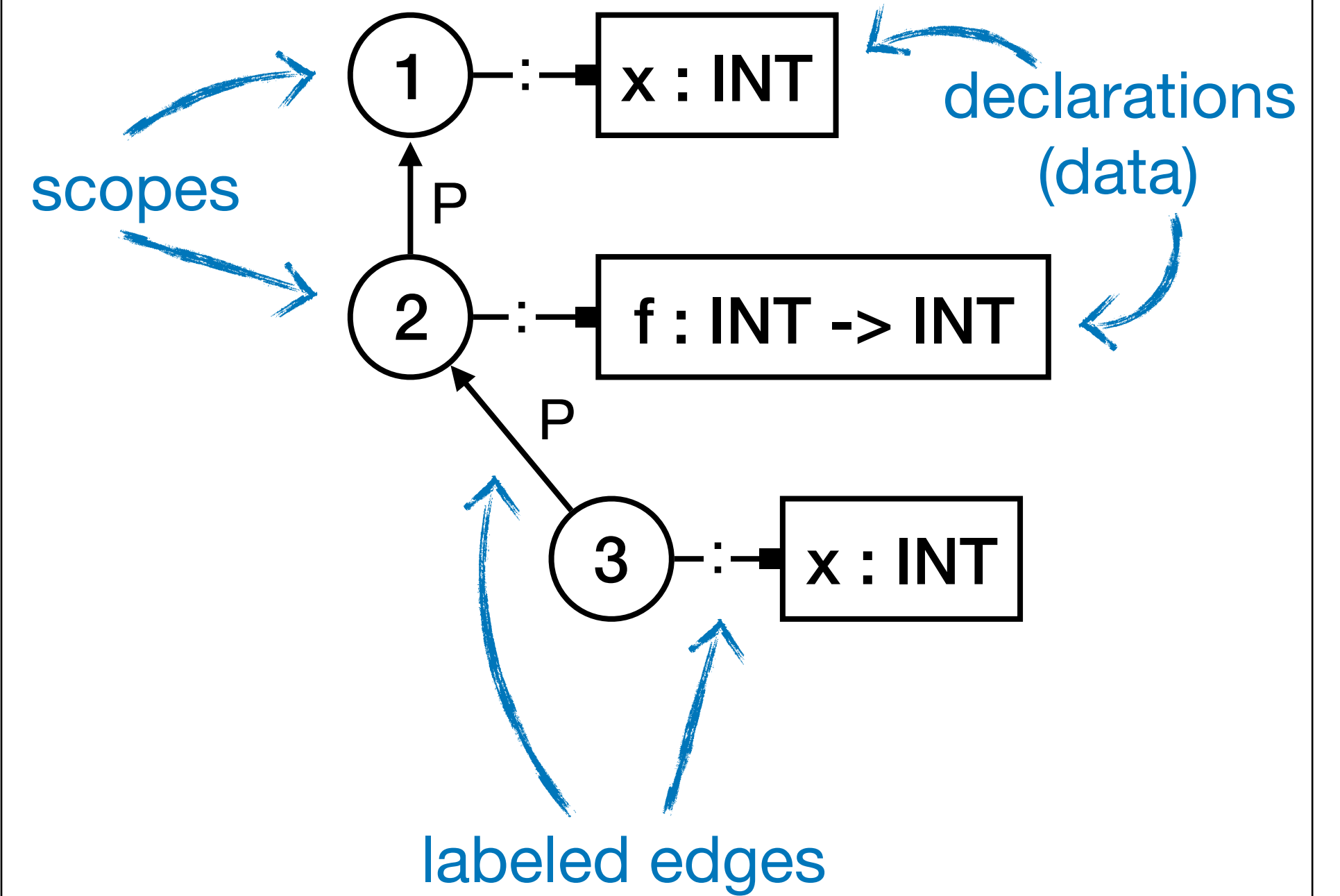
# Our Approach

**Scope Graphs**

**Statix**

# Scope Graph: Lexical

```
let
  x : int = 7
in
  let
    f : int -> int = fun (x:int) { x * 3 }
  in
    f x
```

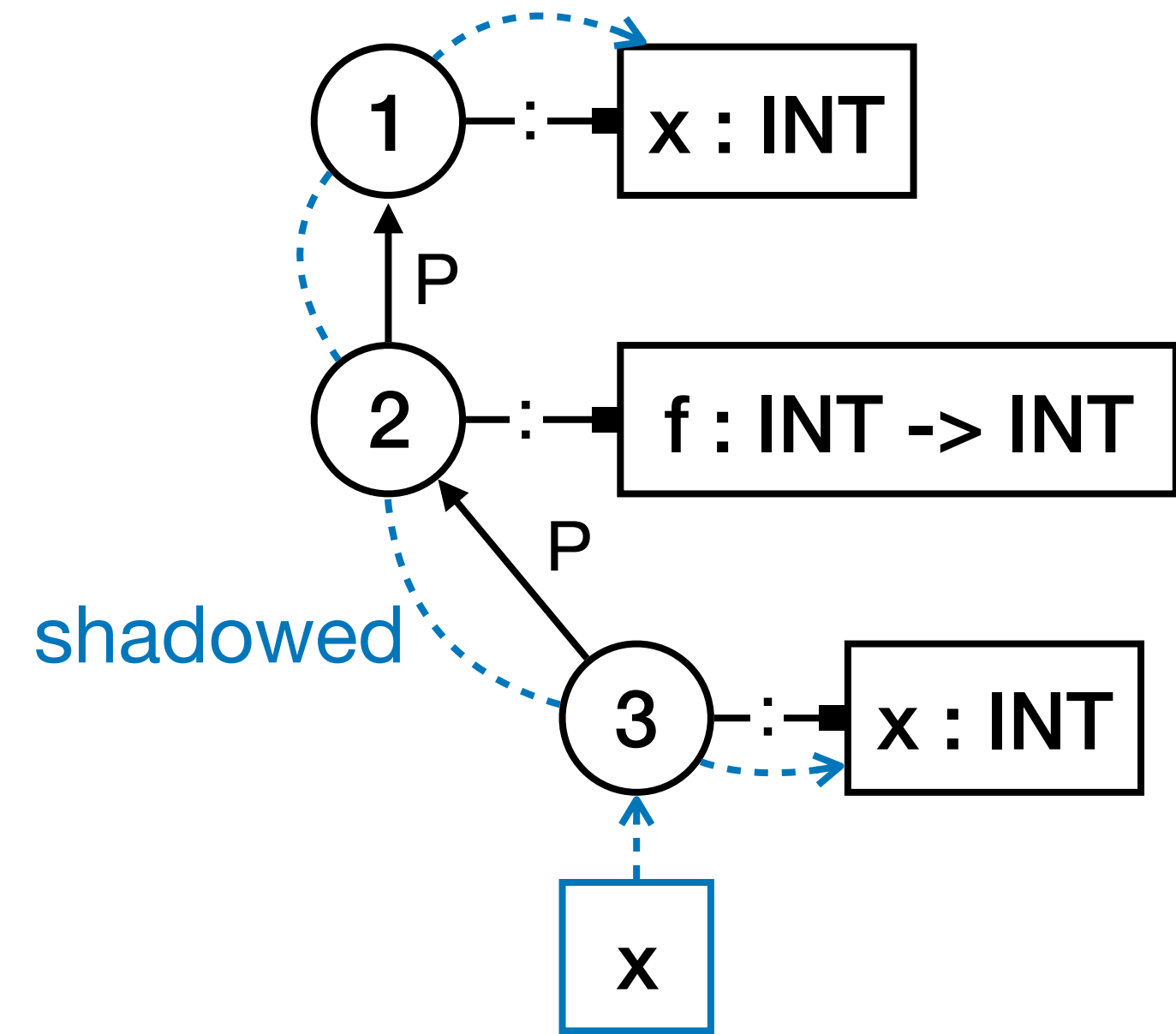




# Scope Graph: Lexical

```
let
  x : int = 7
in
  let
    f : int -> int = fun (x:int) { x * 3 }
  in
    f x
```

Diagram illustrating lexical scoping with shadowing. A dashed blue arrow labeled "shadowed" points from the `x` in the inner function definition to the `x` in the outer `let` binding.



Query

$P^*$  (allow any number of P steps)

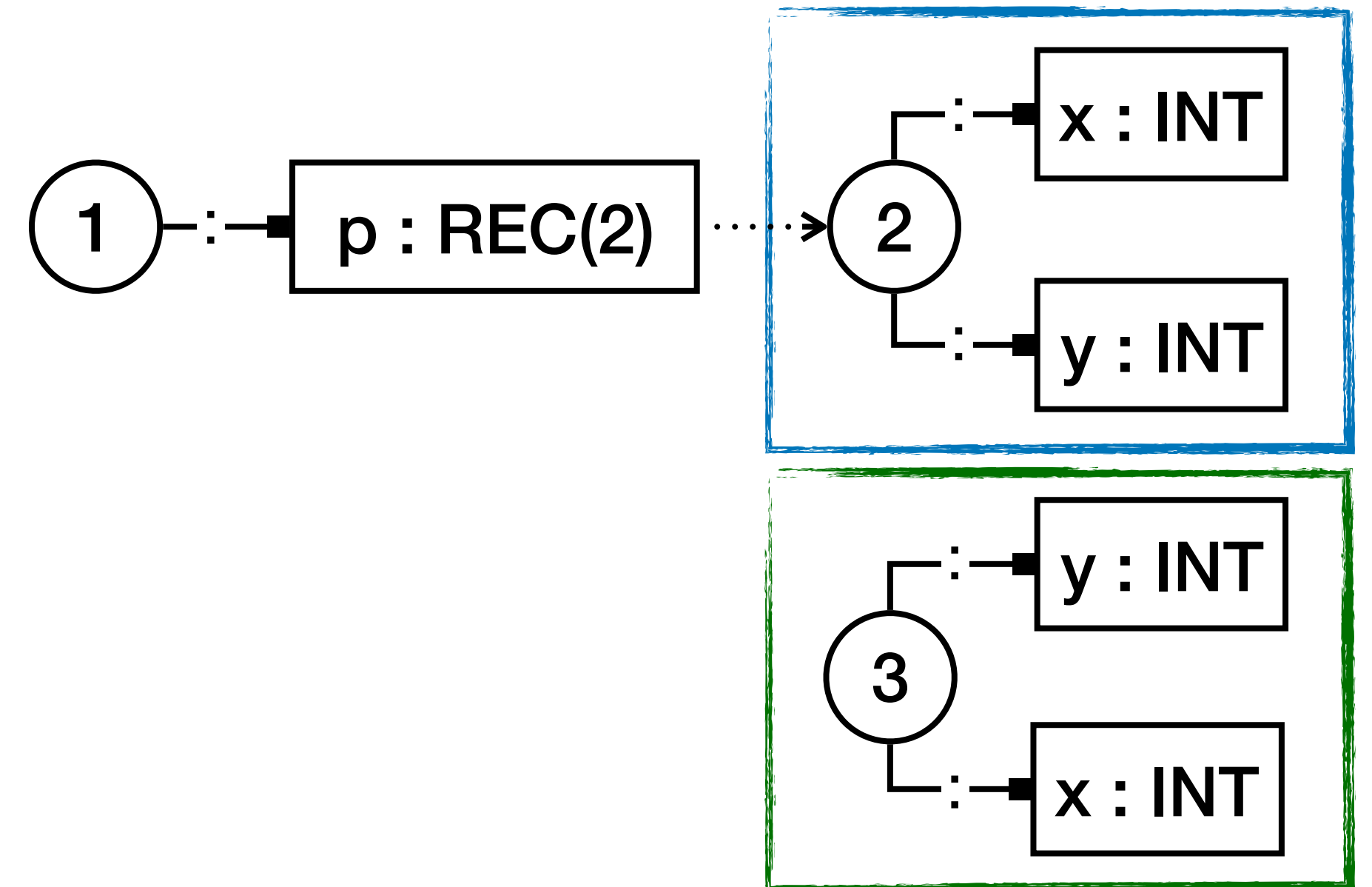
$\$ < P$  (prefer local declarations over P-steps)

- Name resolution = querying the graph
- Visibility and shadowing = regular expression and order over edge labels

# Scope Graph: Records

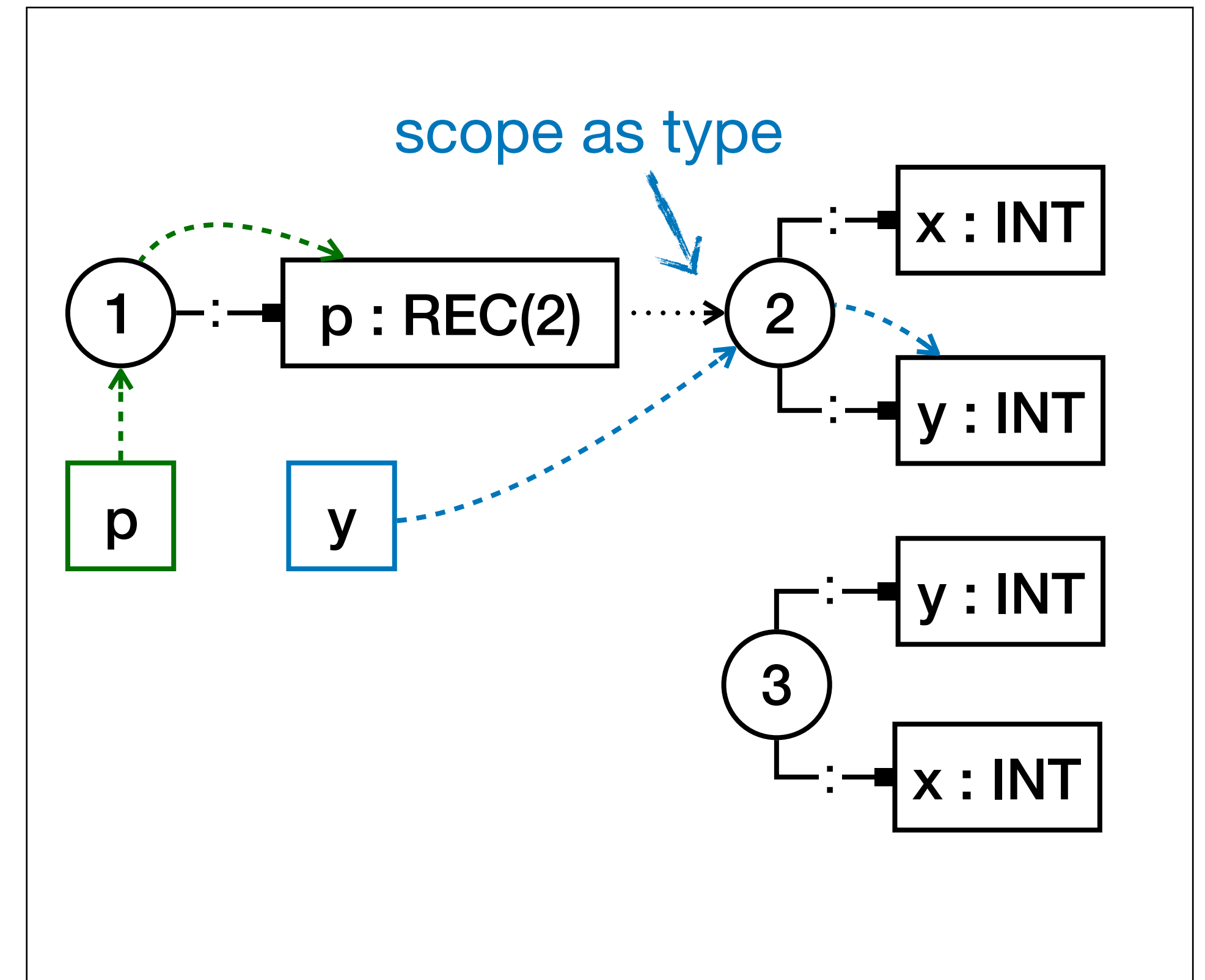
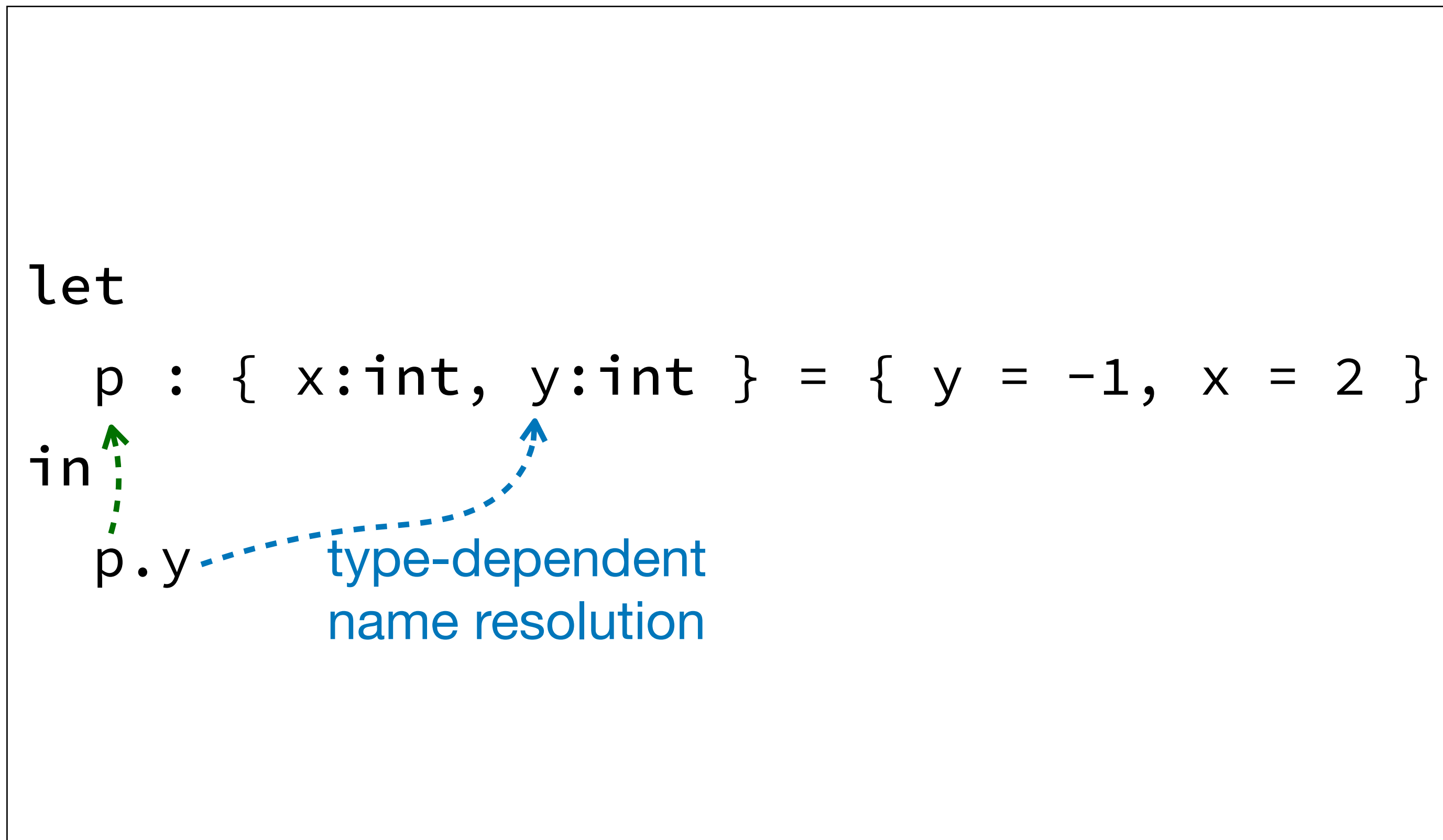
```
let  
  p :  
in  
  p.y
```

`{ x:int, y:int }` = `{ y = -1, x = 2 }`



- Type structure described by scopes

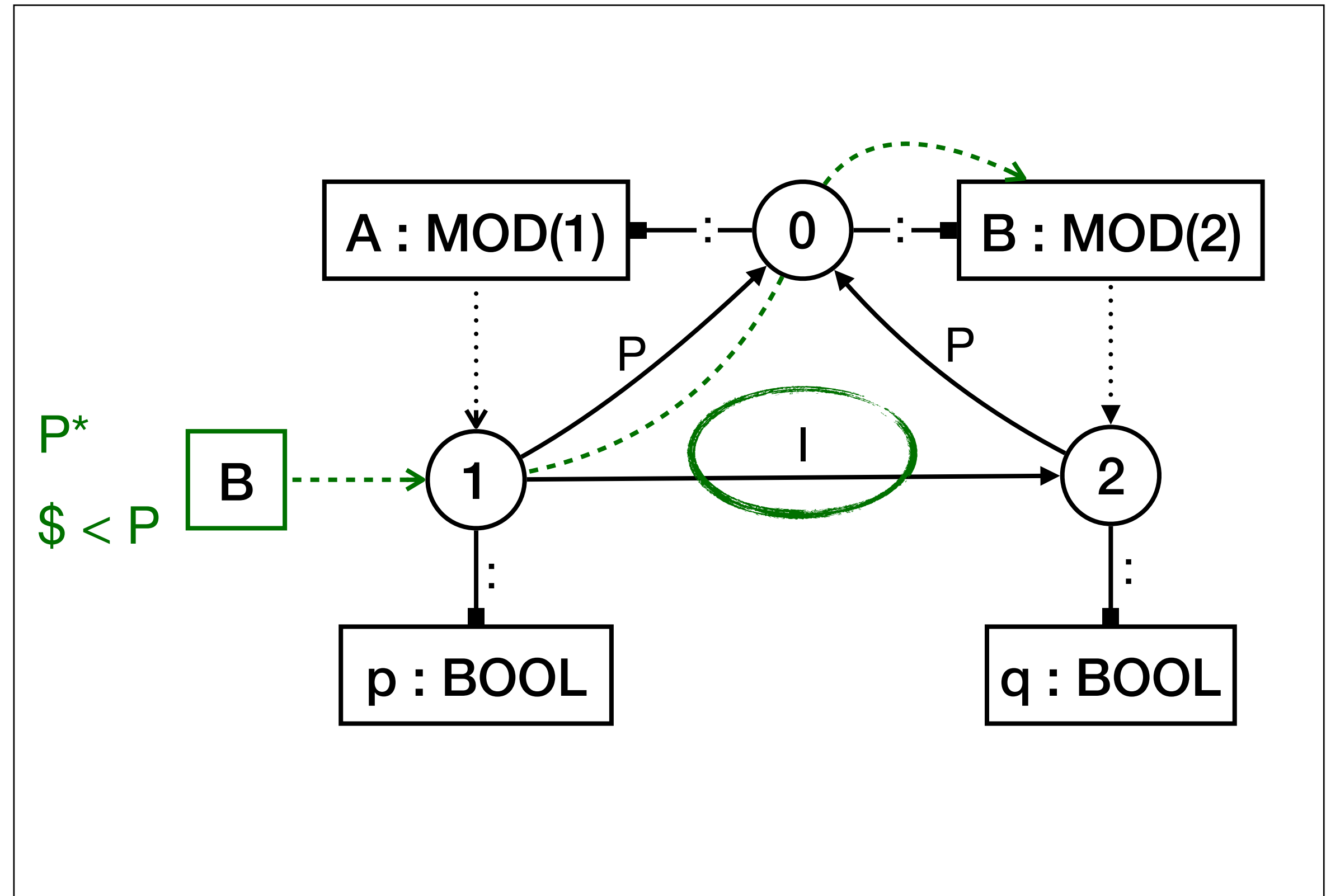
# Scope Graph: Records



- Type structure described by scopes
- Scopes as types = uniform approach to type-dependent name resolution!

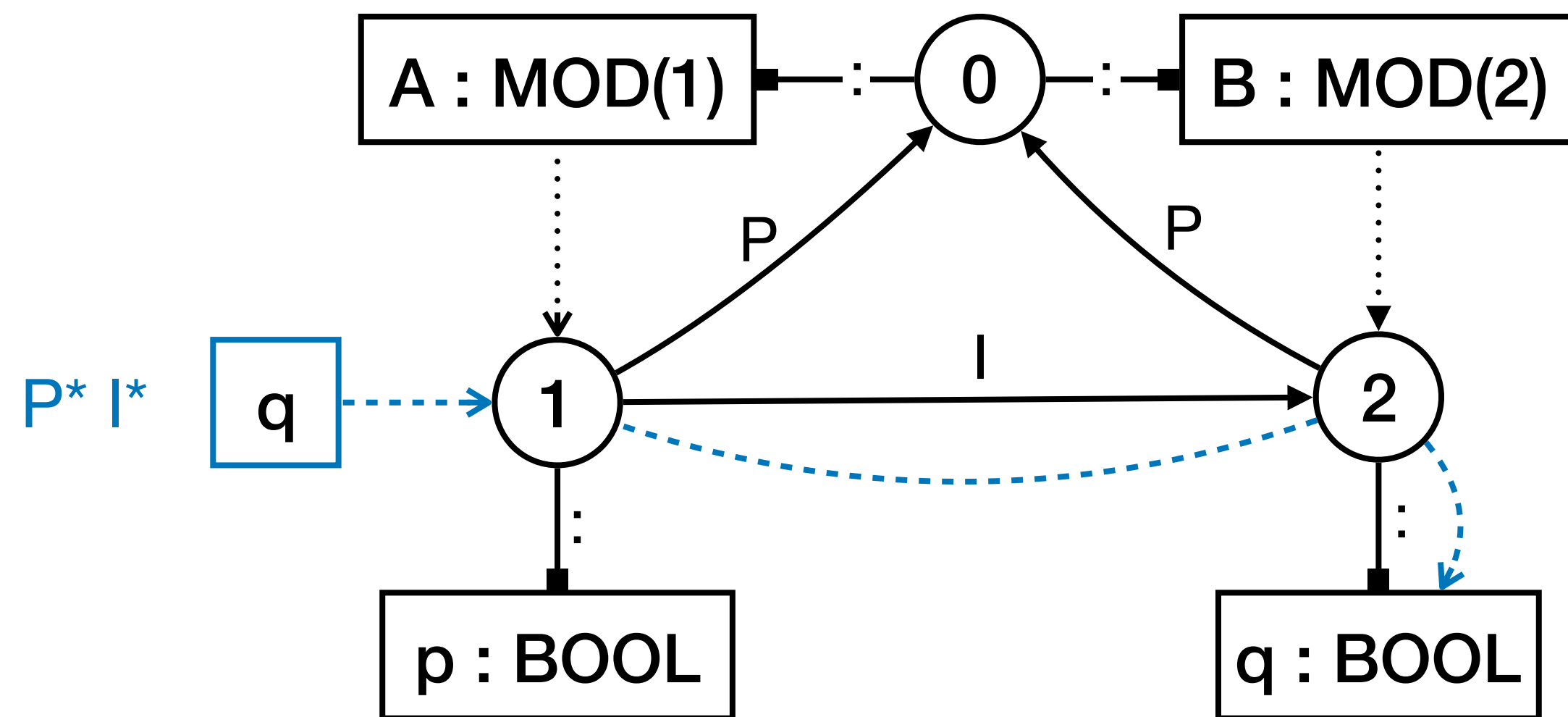
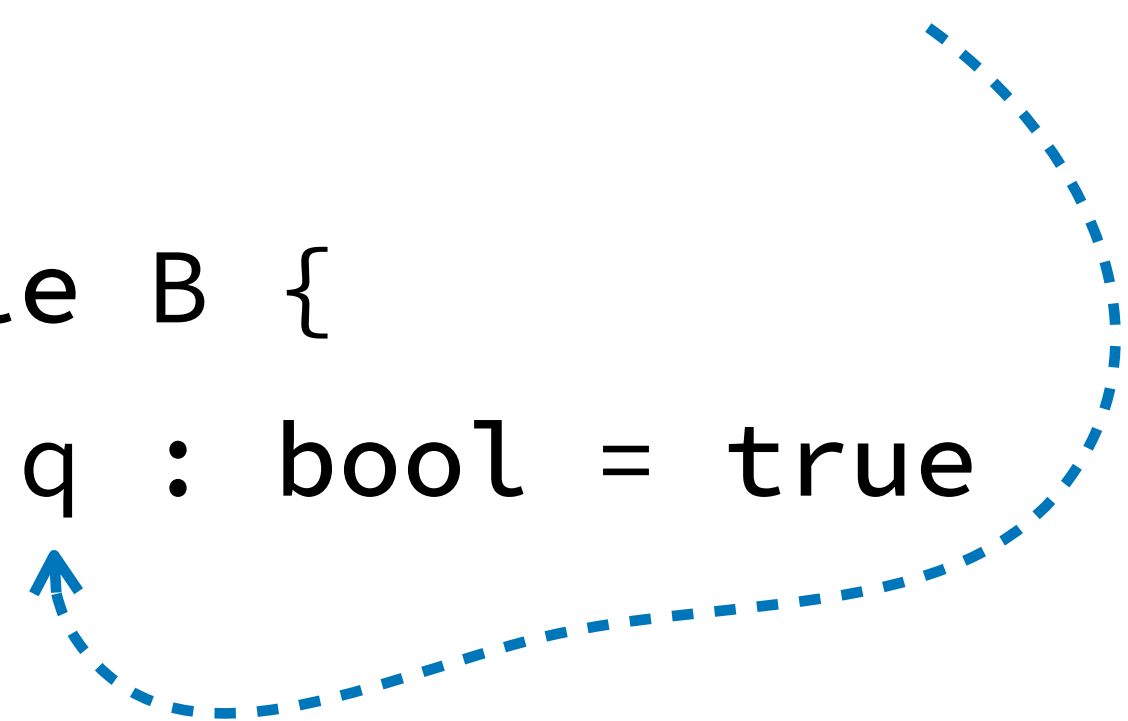
# Scope Graph: Modules

```
module A {  
  import B  
  def p : bool = ~q  
}  
module B {  
  def q : bool = true  
}
```



# Scope Graph: Modules

```
module A {  
  import B  
  def p : bool = ~q  
}  
module B {  
  def q : bool = true  
}
```



# Our Approach

## Scope Graphs

## Statix

Language independent

Capture different kinds of binding

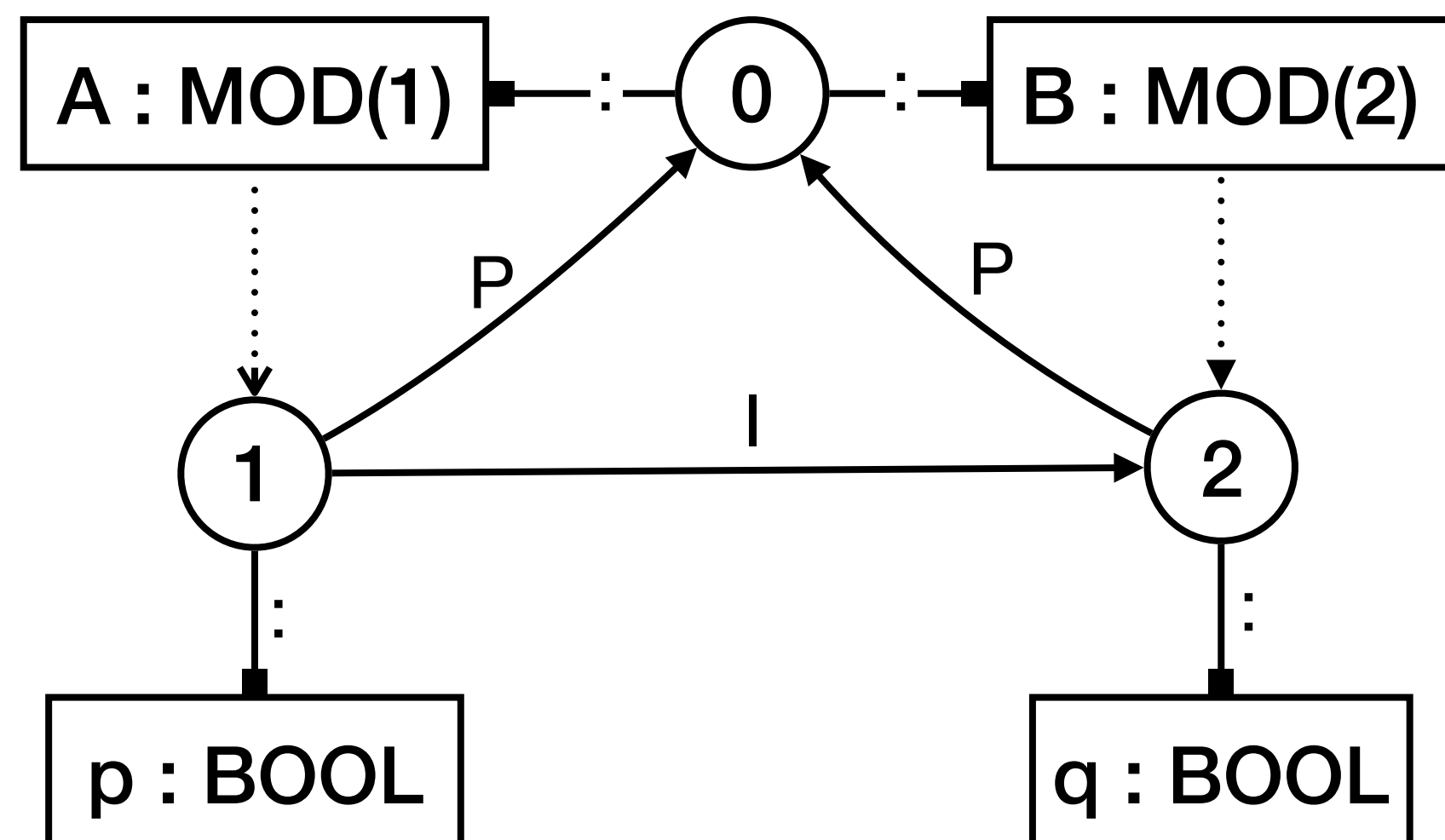
Resolve names by graph queries

# Statix: Declarative Rules

```

module A {
  import B
  def p : bool = ~q
}
module B {
  def q : bool = true
}

```



```

progOk : list(Mod)
progOk(mods) :- {s_prog}
  new s_prog,
  modsOk(s_prog, mods).

```

← predicate signature  
and rules

modsOk **maps** modOk(\*, list(\*))

```

modOk : scope * Mod
modOk(s, Mod(x, defs)) :- {s_mod}
  new s_mod,
  s_mod -P-> s,
  s_mod -> Mod{x@x} with typeOf MOD(s_mod),
  defsOk(s_mod, defs).

```

← syntax-directed  
rules

defsOk **maps** defOk(\*, list(\*))

```

defOk : scope * Def
defOk(s, Import(x)) :- {d s'}
  typeOf of Mod{x@x} in s |-> [(_, (d, MOD(s')))],
  s -I-> s'.

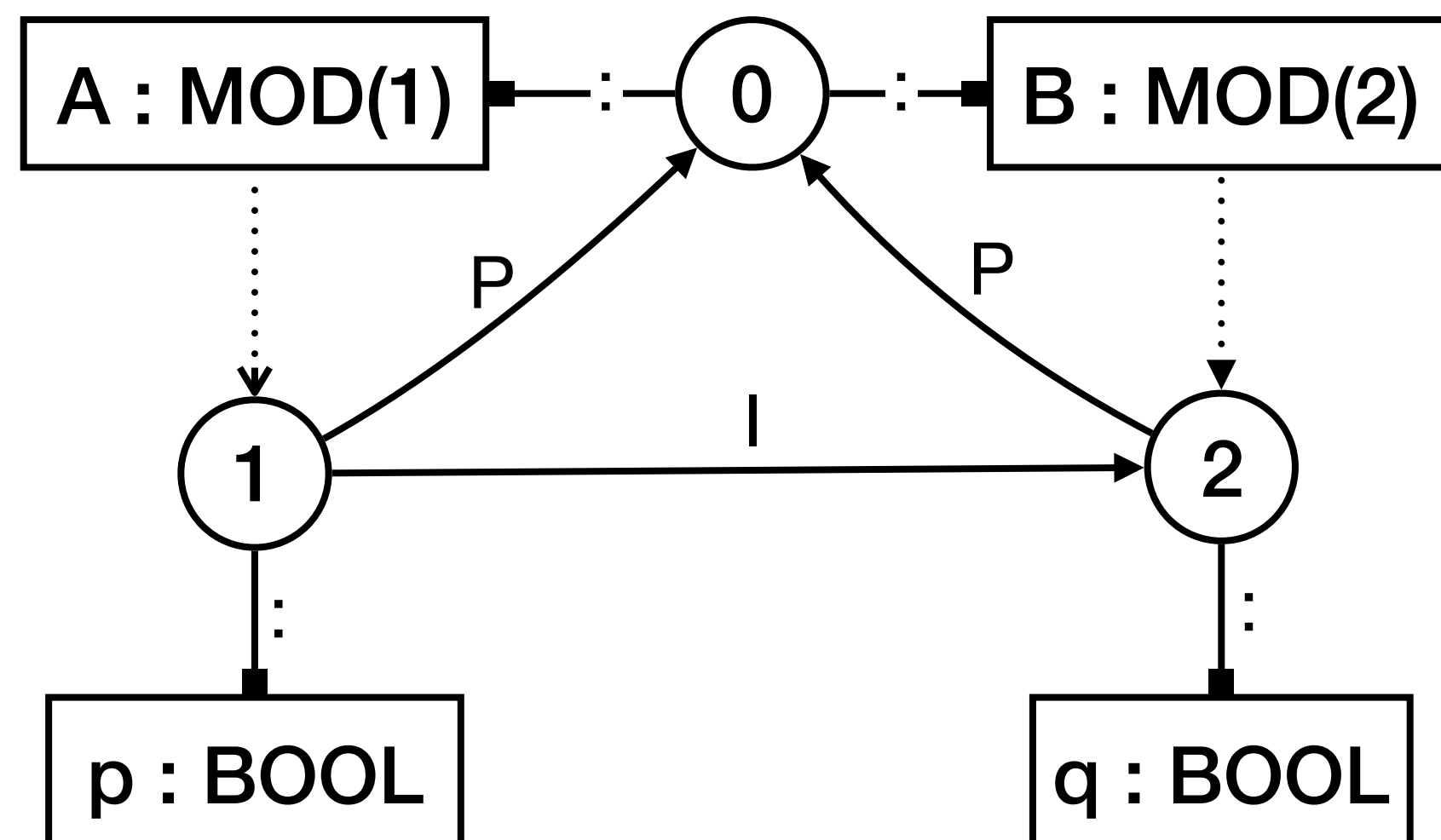
```

# Statix: Declarative Rules

```

module A {
  import B
  def p : bool = ~q
}
module B {
  def q : bool = true
}

```



```

progOk : list(Mod)
progOk(mods) :- {s_prog}
new s_prog, ← scope assertion
modsOk(s_prog, mods).

```

```

modsOk maps modOk(*, list(*))

```

```

modOk : scope * Mod
modOk(s, Mod(x, defs)) :- {s_mod}
new s_mod, ← edge assertion
s_mod -P-> s, ← data assertion
s_mod -> Mod{x@x} with typeOf MOD(s_mod), ←
defsOk(s_mod, defs).

```

```

defsOk maps defOk(*, list(*))

```

```

defOk : scope * Def
defOk(s, Import(x)) :- {d s'}
typeOf of Mod{x@x} in s |-> [(_, (d, MOD(s')))], ← resolution query
s -I-> s'.

```



# Statix: Declarative Rules

```

module A {
  import B
  def p : bool = ~q
}
module B {
  def q : bool = true
}

```

```

progOk : list(Mod)
progOk(mods) :- {s_prog}
  new s_prog,
  modsOk(s_prog, mods).

```

```

modsOk maps modOk(*, list(*))

```

```

modOk : scope * Mod

```

```

modOk(s, Mod(x, defs)) :- {s_mod}

```

```

  new s_mod,
  s_mod -P-> s,
  s_mod -> Mod{x@x} with typeOf MOD(s_mod),
  defsOk(s_mod, defs).

```

```

defsOk maps defOk(*, list(*))

```

```

defOk : scope * Def

```

```

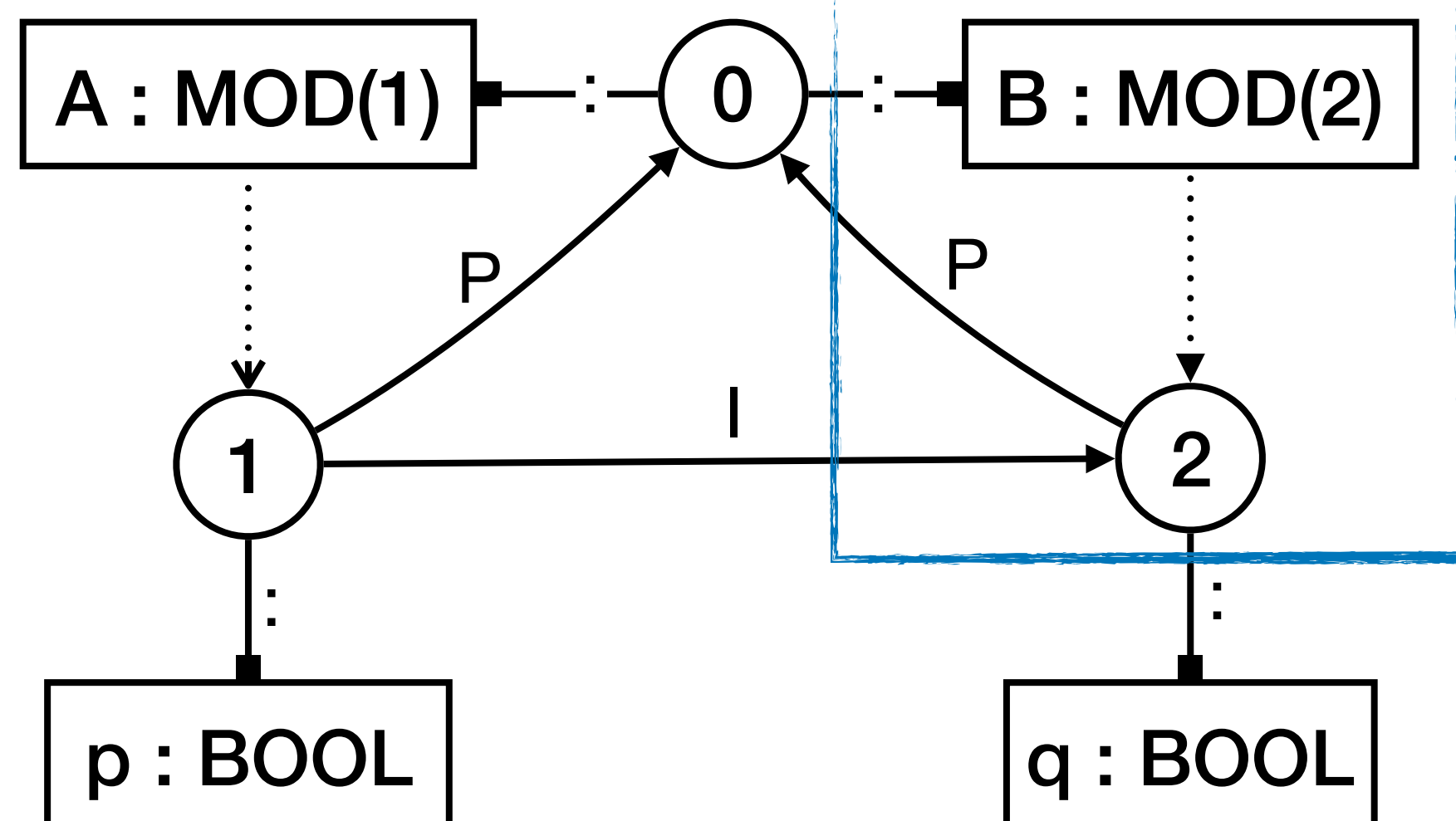
defOk(s, Import(x)) :- {d s'}

```

```

  typeOf of Mod{x@x} in s |-> [(_,(d,MOD(s')))],
  s -I-> s'.

```



# Statix: Declarative Rules

```

module A {
  import B
  def p : bool = ~q
}
module B {
  def q : bool = true
}

```

```

progOk : list(Mod)
progOk(mods) :- {s_prog}
  new s_prog,
  modsOk(s_prog, mods).

modsOk maps modOk(*, list(*))

modOk : scope * Mod
modOk(s, Mod(x, defs)) :- {s_mod}
  new s_mod,
  s_mod -P-> s,
  s_mod -> Mod{x@x} with typeOf MOD(s_mod),
  defsOk(s_mod, defs).

```

```

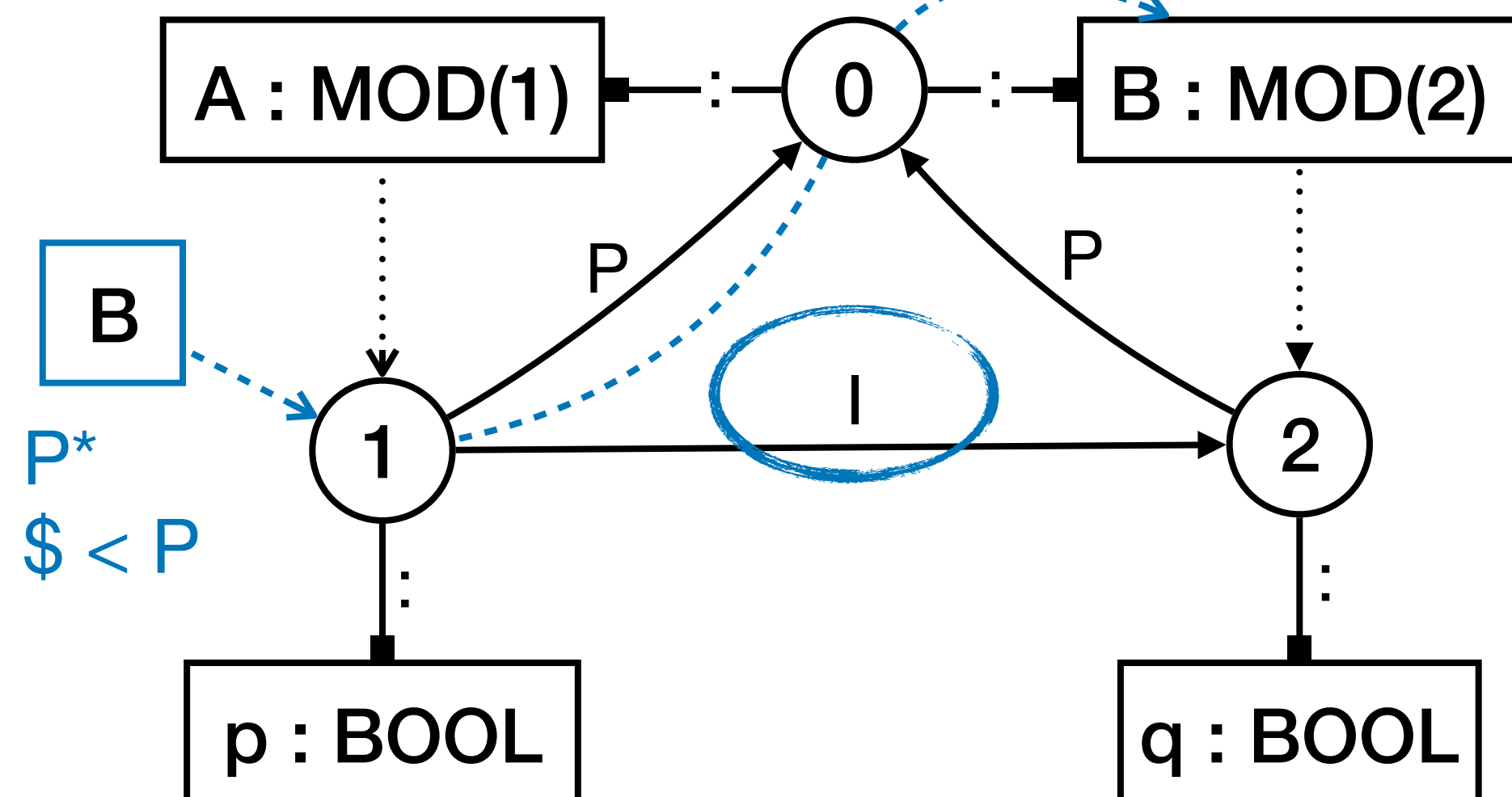
defsOk maps defOk(*, list(*))

```

```

defOk : scope * Def
defOk(s, Import(x)) :- {d s'}
  typeOf of Mod{x@x} in s |-> [(_, (d, MOD(s')))],
  s -I-> s'

```



# Our Approach

## Scope Graphs

Language independent

Capture different kinds of binding

Resolve names by graph queries

## Statix

Declarative specifications

Abstracts over execution order

Constraint solver

# The Meaning of Statix

| $\mathcal{G} \models_{\sigma} C$   |  |  |  |
|--|--|--|--|
| Scope graph $\mathcal{G}$ satisfies constraint $C$ with support $\sigma$   |  |  |  |
| $\frac{}{\mathcal{G} \models_{\perp} \text{emp}}$  | $\frac{\mathcal{G} \models_{\sigma_1} C_1 \quad \mathcal{G} \models_{\sigma_2} C_2}{\mathcal{G} \models_{\sigma_1 \sqcup \sigma_2} C_1 * C_2}$ | $\frac{t_1 = t_2}{\mathcal{G} \models_{\perp} t_1 = t_2}$  | $\frac{\mathcal{G} \models_{\sigma} C[t/x]}{\mathcal{G} \models_{\sigma} \exists x.C}$ |
| $\frac{}{\mathcal{G} \models_{\perp} \text{single}(t, \{t\})}$   | $\frac{\vec{t}' = \min(\vec{t}, R)}{\mathcal{G} \models_{\perp} \min(\vec{t}, R, \vec{t}')} \quad \text{MIN}$                                  | $\frac{}{\mathcal{G} \models_{\perp} \forall x \text{ in } \emptyset.C}$   |  |
| $\frac{\mathcal{G} \models_{\sigma_1} C[t_1/x] \quad \mathcal{G} \models_{\sigma_2} \forall x \text{ in } \vec{t}_2.C}{\mathcal{G} \models_{\sigma_1 \sqcup \sigma_2} \forall x \text{ in } (\{t_1\} \sqcup \vec{t}_2).C}$ | $\frac{s \in S_{\mathcal{G}} \quad \rho_{\mathcal{G}}(s) = t}{\mathcal{G} \models_{(s, \emptyset)} \forall s \rightarrow t}$                   | $\frac{(s_1, l, s_2) \in E_{\mathcal{G}}}{\mathcal{G} \models_{(\emptyset, (s_1, l, s_2))} s_1 \xrightarrow{l} s_2}$ |  |
| $\frac{\mathcal{G} \models_{\sigma} C[\text{Ans}(\mathcal{G}, s \xrightarrow{r} D)/z]}{\mathcal{G} \models_{\sigma} \text{query } s \xrightarrow{r} D \text{ as } z.C}$  |  | $\frac{\rho_{\mathcal{G}}(s) = t}{\mathcal{G} \models_{\perp} \text{dataOf}(s, t)}$                                  |  |

Declarative Semantics

| $\kappa \rightarrow \kappa'$  |  | State $\kappa$ steps to $\kappa'$ |
|---|--|-----------------------------------|
| $\frac{}{\langle \mathcal{G} \mid (C_1 * C_2); \vec{C} \rangle \rightarrow \langle \mathcal{G} \mid C_1; C_2; \vec{C} \rangle}$   | $\frac{t_1 \varphi = t_2 \varphi \quad \varphi \text{ is most general}}{\langle \mathcal{G} \mid (t_1 = t_2); \vec{C} \rangle \rightarrow \langle \mathcal{G} \varphi \mid \vec{C} \varphi \rangle}$ |                                   |
| $\frac{\neg \exists \varphi. t_1 \varphi = t_2 \varphi}{\langle \mathcal{G} \mid (t_1 = t_2); \vec{C} \rangle \rightarrow \langle \mathcal{G} \mid \{\text{false}\} \rangle}$                               | $\frac{y \text{ is fresh for } \mathcal{G} \text{ and } \vec{C}}{\langle \mathcal{G} \mid (\exists x.C); \vec{C} \rangle \rightarrow \langle \mathcal{G} \mid C[y/x]; \vec{C} \rangle}$              |                                   |
| $\frac{}{\langle \mathcal{G} \mid \text{single}(t, \{t'\}); \vec{C} \rangle \rightarrow \langle \mathcal{G} \mid (t = t'); \vec{C} \rangle}$  | $\frac{\neg \exists t'. \vec{t} = \{t'\}}{\langle \mathcal{G} \mid \text{single}(t, \vec{t}); \vec{C} \rangle \rightarrow \langle \mathcal{G} \mid \{\text{false}\} \rangle}$                        |                                   |
| $\frac{s \notin S}{\langle \langle S, E, \rho \rangle \mid (\forall x \rightarrow t); \vec{C} \rangle \rightarrow \langle \langle (s; S), E, \rho[s \rightarrow t][s/x] \rangle \mid \vec{C}[s/x] \rangle}$ |  |                                   |
| $\frac{t_2 \text{ is not a variable}}{\langle \mathcal{G} \mid (\forall t_2 \rightarrow t_1); \vec{C} \rangle \rightarrow \langle \mathcal{G} \mid \{\text{false}\} \rangle}$                               | $\frac{\rho(s) = t_2}{\langle \mathcal{G} \mid \text{dataOf}(s, t_1); \vec{C} \rangle \rightarrow \langle \mathcal{G} \mid (t_1 = t_2); \vec{C} \rangle}$  |                                   |
| $\frac{}{\langle \langle S, E, \rho \rangle \mid (s_1 \xrightarrow{l} s_2); \vec{C} \rangle \rightarrow \langle \langle S, (s_1, l, s_2), E, \rho \rangle \mid \vec{C} \rangle}$                            |  |                                   |

Small-step Operational Semantics

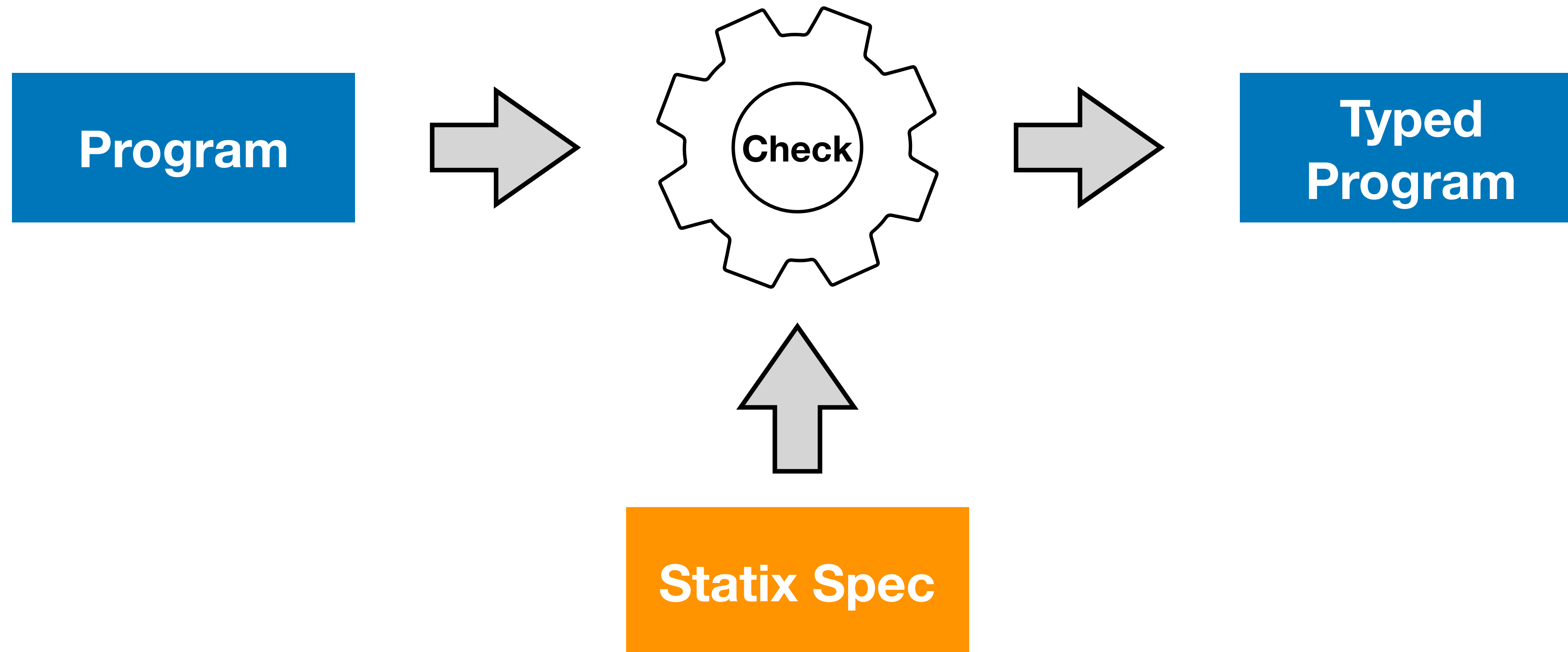
```

78 -- | Try to solve a focused constraint.
79 -- This should not be a recursive function, as not to infer with scheduling.
80 solveFocus :: Constraint1 -> SolverM s ()
81
82 solveFocus (CTrue _) = return ()
83 solveFocus (CFalse _) = unsatisfiable "Say hello to Falso"
84
85 solveFocus (CEq _ t1 t2) = do
86   t1' <- toDag t1
87   t2' <- toDag t2
88   escalateUnificationError $ unify t1' t2'
89   next
90
91 solveFocus (CNotEq _ t1 t2) = do
92   escalateUnificationError $ passesGuard (GNotEq t1 t2)
93   next
94
95 solveFocus (CAnd _ l r) = do
96   newGoal l
97   newGoal r
98
99 solveFocus (CEx _ ns c) =
100   openExist ns (newGoal c)
101
102 solveFocus (CNew _ x d) = do
103   t <- resolve x
104   d <- toDag d
105   u <- newNode d
106   t' <- construct (Tm (SNodeF u))
107   catchError
108     (unify t t')
109     (\ err -> unsatisfiable "Cannot get ownership of existing node")
110   next
111

```

Implementation  
(Java & Haskell)

# Type Checking with Statix



# Literature

## Scope Graphs and Static Semantics

- Néron Pierre, Andrew Tolmach, Eelco Visser, and Guido Wachsmuth. *A Theory of Name Resolution*. ESOP 2015.
- Hendrik van Antwerpen, Pierre Néron, Andrew Tolmach, Eelco Visser, and Guido Wachsmuth. *A Constraint Language for Static Semantic Analysis Based on Scope Graphs*. PEPM 2016.
- Hendrik van Antwerpen, Casper Bach Poulsen, Arjen Rouvoet, and Eelco Visser. *Scopes As Types*. OOPSLA 2018.

## Scope Graphs and Dynamic Semantics

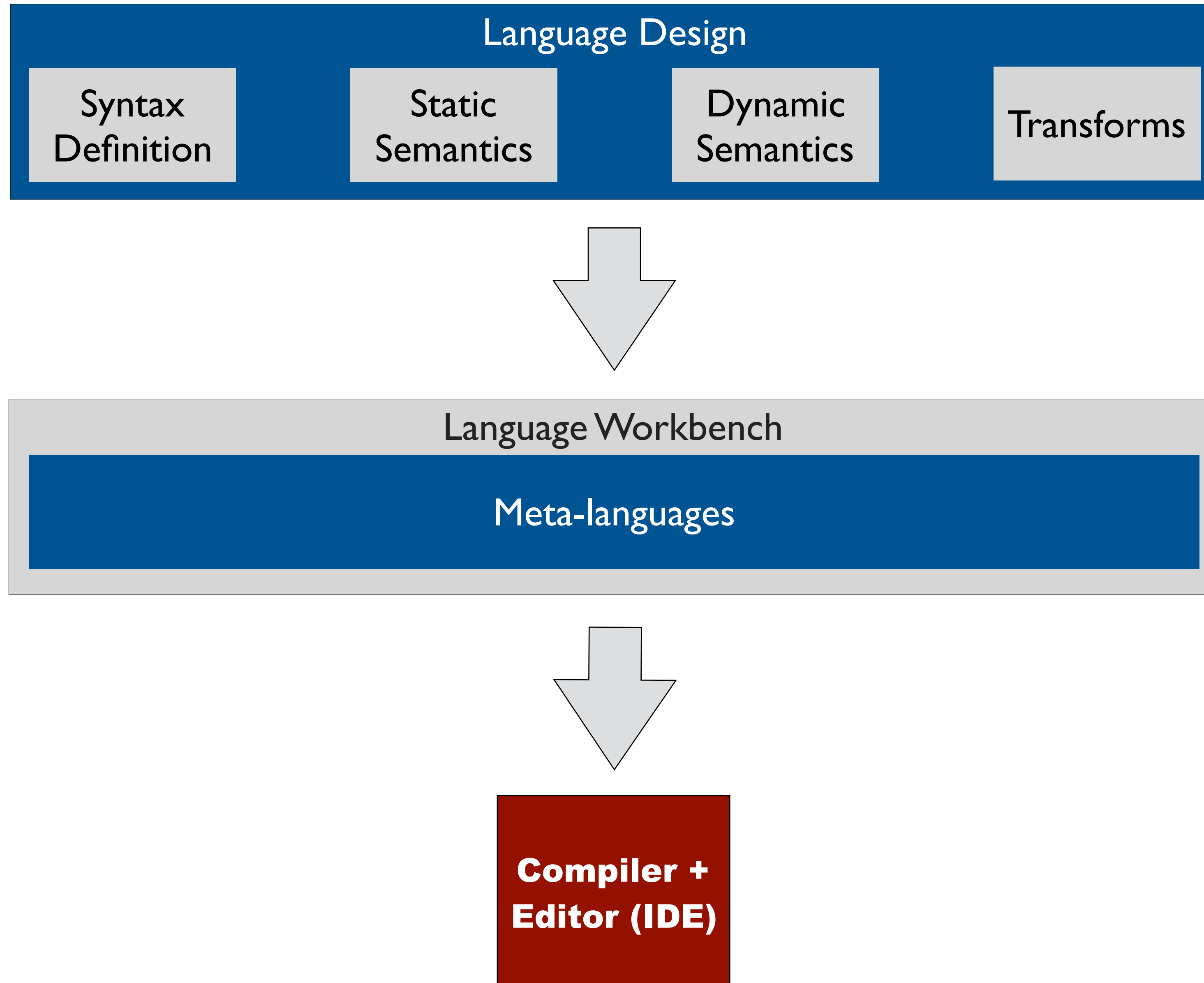
- Casper Bach Poulsen, Pierre Néron, Andrew Tolmach, and Eelco Visser. *Scopes Describe Frames: A Uniform Model for Memory Layout in Dynamic Semantics*. ECOOP 2016.
- Casper Bach Poulsen, Arjen Rouvoet, Andrew Tolmach, Robbert Krebbers, and Eelco Visser. *Intrinsically-Typed Definitional Interpreters for Imperative Languages*. POPL 2018.

## Scope Graphs and IDEs

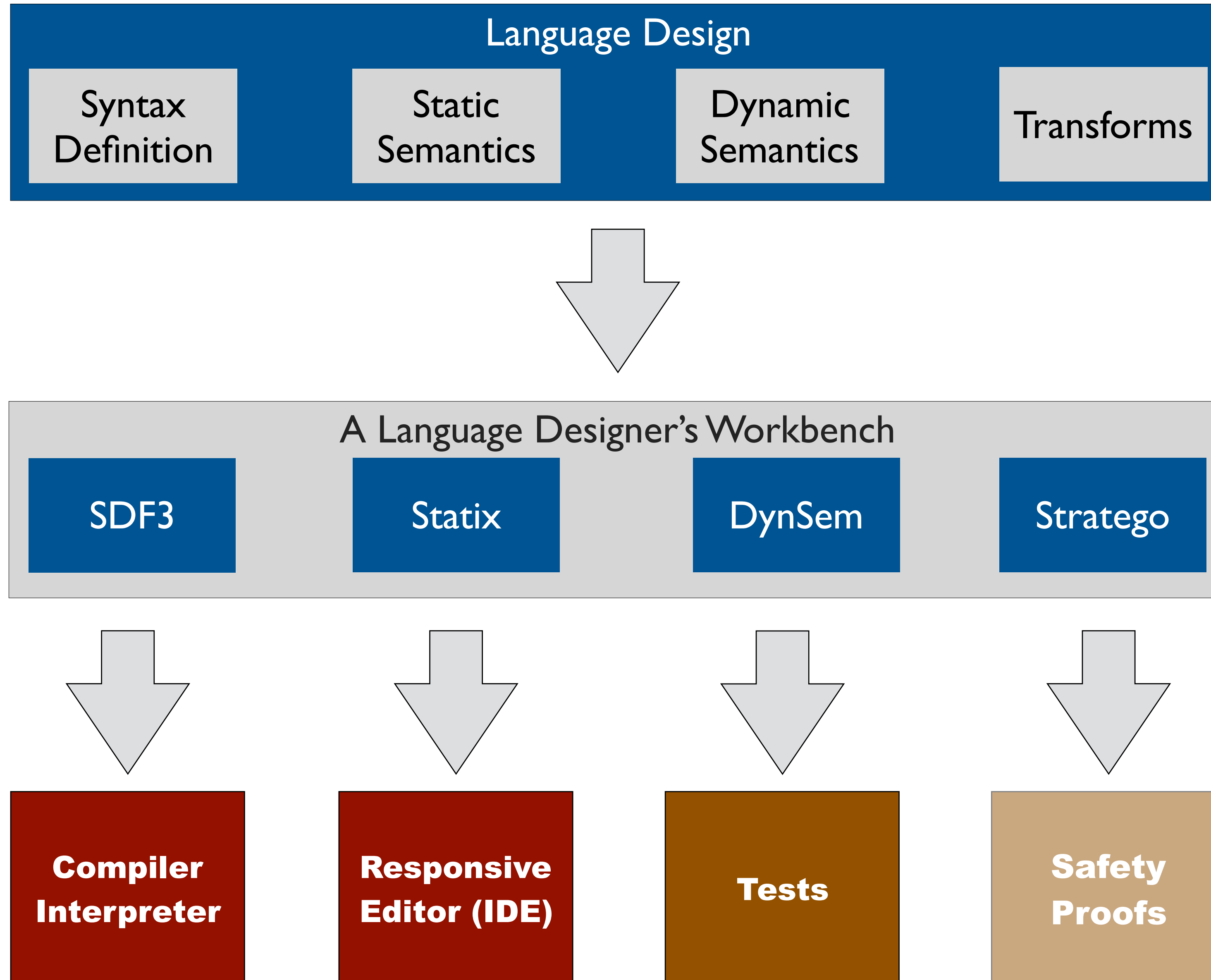
- Daniël A. A. Pelsmaeker, Hendrik van Antwerpen, and Eelco Visser. *Towards Language-Parametric Semantic Editor Services Based on Declarative Type System Specifications (Brave New Idea Paper)*. ECOOP 2019



# Spoofax Language Workbench



# Spooifax Language Workbench





# Language Testing

## Questions about your language definition

- Is type system sound w.r.t. the interpreter?
- Does optimizing compiler preserve program behavior?
- Is student compiler equivalent to reference?

## Answer by proving

- Finding proof can be hard, time-consuming
- Few people have the required knowledge

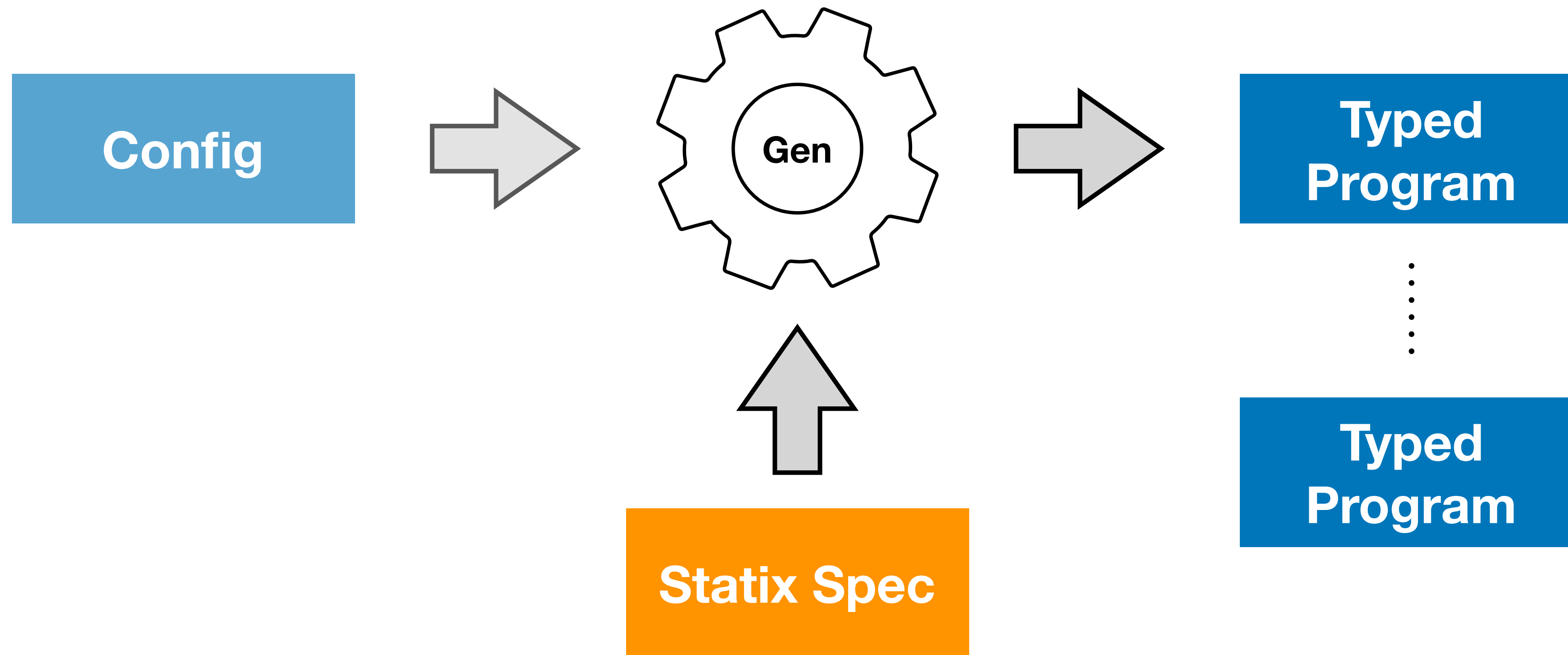
## Answer by testing

- Creating good tests can be hard, time-consuming
- Feasible for more people

## Answer by property-based testing

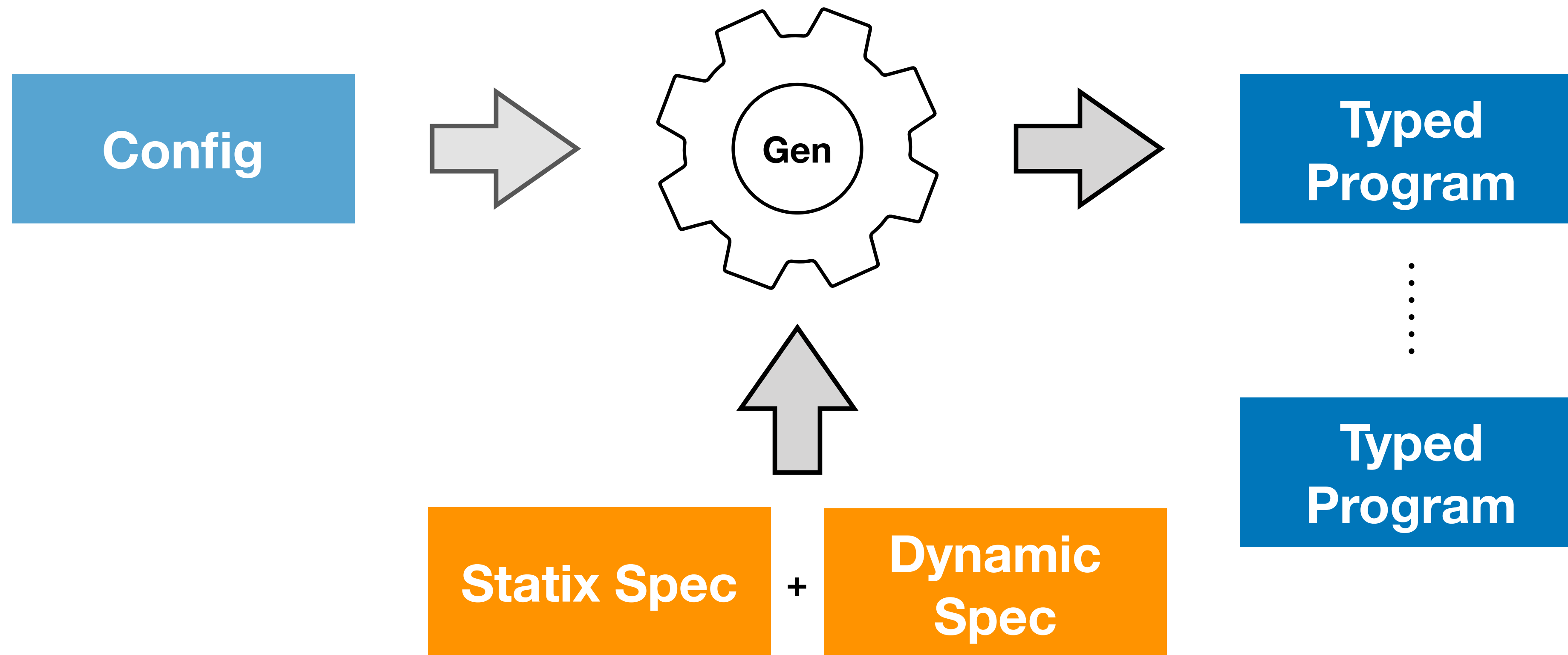
- Generate well-formed programs as test inputs
- (Semi-)automatic tool

# Generating Well-Typed Programs with Statix



Do generated program have interesting execution behavior?  
Do they not immediately terminate?

# Generating Well-Typed Programs with Statix



Simulate execution of generated program during search  
Prune uninteresting programs early

# Generating Well-Typed Programs with Statix

## Goal

- Random generation of well-typed programs from Statix specifications

## Application

- Testing runtime behavior (compilers, interpreters)

## Evaluation

- Use MiniJava language (small, but non-lexical scoping)
- Test student compilers (of which we have many) against a reference compiler

## Technical Challenges

- Add search to the Statix solver (now only forward reasoning inference)
- Non-locality of names (declarations and references far apart in AST)
- Ensure interesting execution behavior in generated programs